
Exercise Sheet 6 (Chapter 8)

Chapter 8

Exercise 1. Poincaré metric

Feel free to take $n = 2$ in this exercise. You can always do the general case afterwards.

- (1) Recover the expression of the stereographic projection $s: \mathcal{H}^+ \rightarrow B^n$.
- (2) Recall the expressions of the Riemannian metrics $g_{\mathcal{H}^+}$ and g_{B^n} and recover the fact that s is a Riemannian isometry.
- (3) Recover the expression of the Cayley transform $c: H^n \rightarrow B^n$.
- (4) Recall the expression of the metric g_{H^n} and recover that c is a Riemannian isometry.

Exercise 2. Curvature of the Poincaré metric

Let $\Omega \subseteq \mathbb{R}^n$ and let $g = e^{2\varphi} g_0$ be a conformal metric in Ω . Let u, v be an orthonormal pair of vectors in \mathbb{R}^n and denote P the plane spanned by u and v . The following formula (reference: [?]) gives the sectional curvature of the metric g at a point $x \in \Omega$ in the direction of P :

$$K_P = -e^{-2\varphi} \left[D^2\varphi(u, u) + D^2\varphi(v, v) + \|\nabla\varphi\|^2 - \langle \nabla\varphi, u \rangle^2 - \langle \nabla\varphi, v \rangle^2 \right].$$

(We have denoted $\nabla\varphi$ the gradient of φ .)

- (1) Recover the curvature of the Poincaré metric in B^n by direct computation.
- (2) Let $K < 0$. Can you find a metric of constant sectional curvature K in B^n ?
- (3) Same questions for H^n .

Exercise 3. Poincaré vs Klein ball

- (1) Show that the natural identification between the Poincaré ball and the Beltrami-Klein ball is given by the map

$$\begin{aligned} \varphi: B_{\text{P}}^n &\longrightarrow B_{\text{K}}^n \\ x &\longmapsto \frac{2x}{1 + \|x\|^2}. \end{aligned}$$

- (2) Recover that φ is a Riemannian isometry by direct computation. *Feel free to take $n = 2$.*

Exercise 4. Poincaré vs Klein ball: the distance

- (1) Let x, x' be two real numbers in $[0, 1)$ such that $x' = \frac{2x}{1+x^2}$. Show that $\frac{1+x'}{1-x'} = \left(\frac{1+x}{1-x}\right)^2$ and derive that $\operatorname{artanh} x' = 2 \operatorname{artanh} x$.
- (2) Recover the fact that the map φ of [Exercise 3](#) is a metric isometry, i.e. $d(\varphi(x), \varphi(y)) = d(x, y)$, in the case $y = 0$.

Exercise 5. Poincaré vs Klein ball: isometries

$\operatorname{PO}(n, 1)$ acts by isometries on the Klein ball and the Poincaré ball. Is this the same action on B^n ? Show that the map φ of [Exercise 3](#) conjugates the two actions.

Exercise 6. Hemisphere model

Let S^n be the unit sphere in \mathbb{R}^{n+1} and denote S_+^n the upper hemisphere (with $x_{n+1} > 0$). We also denote $S = (0, \dots, 0, -1)$ the “South pole” of S^n . We recall that the Poincaré ball may be seen as the unit ball in $\mathbb{R}^n \subseteq \mathbb{R}^{n+1}$.

- (1) Consider the stereographic projection $s: S^n \rightarrow \widehat{\mathbb{R}^n}$. Find its analytic expression. Show that s restricts to a diffeomorphism $S_+^n \rightarrow B^n$.
- (2) By definition, the *hemisphere model* $(S_+^n, g_{S_+^n})$ of hyperbolic space is the inverse image of the Poincaré ball (B^n, g_{B^n}) by the stereographic projection s . Prove that $g_{S_+^n}$ can be written:

$$ds^2 = \frac{dx_1^2 + \dots + dx_{n+1}^2}{x_{n+1}^2}.$$

In what sense is the hemisphere model a conformal model?

Exercise 7. Relations between models

- (1) Show that the different models of hyperbolic space are related as showed by the diagram in [Figure 1](#).
- (2) Show that geodesics in the hemisphere model are semi-circles that are orthogonal to the equator. Explain [Figure 2](#).
- (3) Recover that geodesics in the Poincaré half-space model are semi-circles that are orthogonal to the boundary.

Exercise 8. Matrix model of hyperbolic 3-space

Let H denote the set of 2×2 matrices with complex coefficients that are Hermitian symmetric:

$$H = \{A \in \mathcal{M}_{2 \times 2}(\mathbb{C}) \mid A^* = A\}$$

where we denote $A^* = {}^t\bar{A}$.

- (1) Let $q(A) = -\det(A)$. Show that $q(A)$ is a quadratic form on H , with associated symmetric bilinear form $b(A, B) = -\frac{1}{2} \operatorname{tr}(A {}^t\operatorname{Comat}(B))$.
- (2) Show that (H, b) is isomorphic to $\mathbb{R}^{3,1}$ via

$$(x_1, x_2, x_3, x_4) \mapsto \begin{bmatrix} x_1 + x_4 & x_2 + ix_3 \\ x_2 - ix_3 & x_1 - x_4 \end{bmatrix}.$$

- (3) Let $H_1 = H \cap \operatorname{SL}(2, \mathbb{C})$. Show that H_1 is a model of hyperbolic 3-space. What is the Riemannian metric?
- (4) Show that $\operatorname{SL}(2, \mathbb{C})$ acts on H_1 by isometries via $M \cdot A = M A M^*$. What is the stabilizer of I_2 ? Recover that $\operatorname{Isom}^+(\mathbb{H}^3) \approx \operatorname{PSL}(2, \mathbb{C})$ and $\mathbb{H}^3 \approx \operatorname{PSL}(2, \mathbb{C})/\operatorname{PSU}(2)$.

Exercise 9. Hyperbolic subspace

Propose a definition of a hyperbolic subspace of a hyperbolic space $X = \mathbb{H}^n$, and describe the hyperbolic subspaces in all the different models of \mathbb{H}^n .

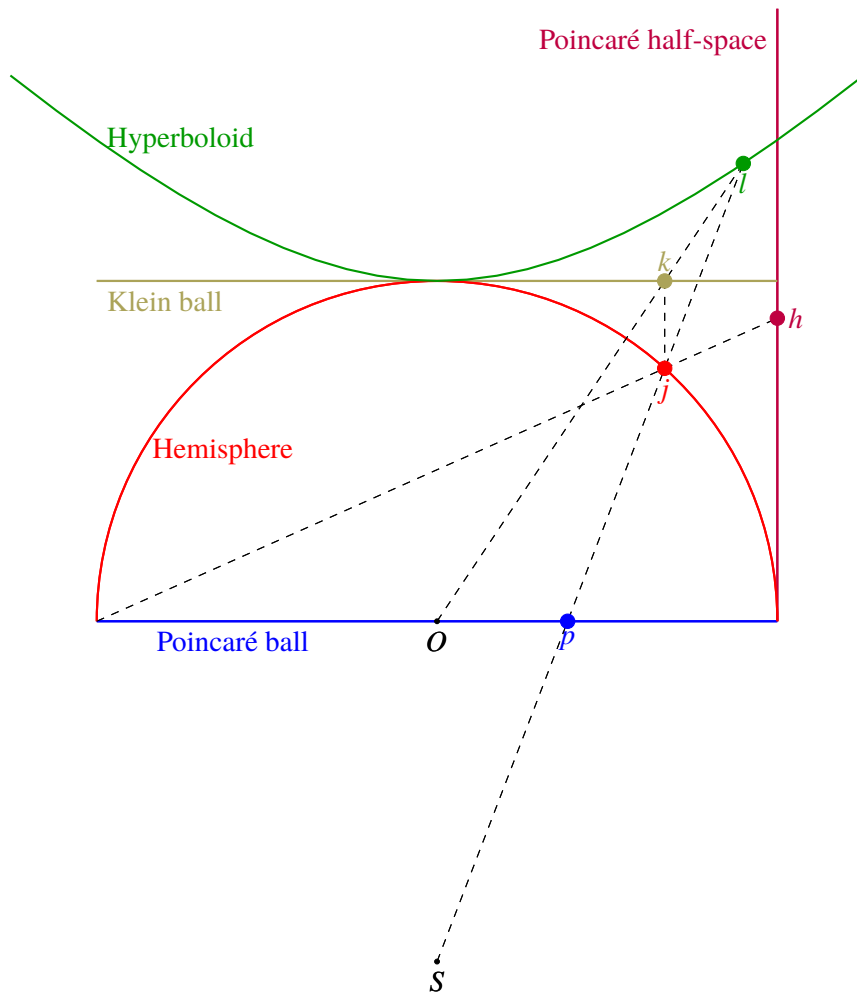


Figure 1: Relation between models of hyperbolic space.

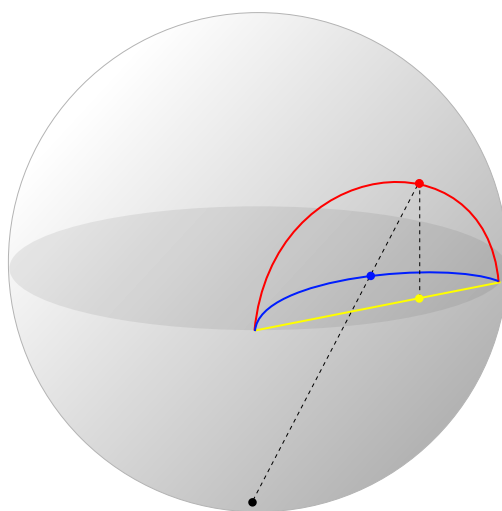


Figure 2: Geodesics in Poincaré ball, Klein ball, and hemisphere models.